

Anurag Bagchi

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Experience

Carnegie Mellon University

Pittsburgh

RESEARCH ASSISTANT UNDER DR. MARTIAL HEBERT

Aug 2023 - Present

- Leveraging **Text-to-Video** & **Text-to-Image Diffusion models** for **Video understanding** and **Robotics** tasks in collaboration with **Toyota research institute**

Bytedance AI Lab

Singapore

COMPUTER VISION ENGINEER, TIKTOK BRAND SAFETY

March 2023 - Aug 2023

- I worked in **Prof. Song Bai's** team, where I have **launched 11 Multi-Modal** models using **Vision, Audio** and **text** for various challenging policy detection tasks and **automated** the iteration process for **21 ASR models**.

TikTok R&D Singapore

Singapore

MACHINE LEARNING ENGINEER, VIDEO & PUSH RECOMMENDATION

March 2021 - Feb 2023

- Created new recommendation models and improved existing ones to significantly increase, **DAU (+0.07%)**, **user staytime(+3%)**, **click-through-rate (+15%)** and reduce **system latency(-3%)** and **memory-usage(-2.5%)**.
- Researched, developed and modified the entire ML pipeline, including problem formulation, feature engineering, model design and implementation, experimentation, analysis and deployment for different use-cases.

IIIT Hyderabad

Hyderabad, India

RESEARCH ASSISTANT UNDER DR. RAVI KIRAN AND DR. MAKARAND TAPASWI, CVIT

Oct 2020 - Feb 2021

- Proposed and implemented a multi-modal setup for **Temporal Action Localisation (TAL)** task that achieved new SoTA on **ActivityNet-v1.3** and **Thumos14** datasets by a margin of **3.04%** and **1.02%** respectively.
- Extensively investigated **Graph Networks, Transformers** and **Vision-language** models using high-performance clusters.

Samsung Research

Bangalore, India

INTERN, IMAGING R&D TEAM

May 2019 - July 2019

- Received a **Full time offer** for modifying different functions in the mobile camera service suite using depth data.
- I was also awarded the **Samsung Advanced Certificate** for my programming skills

Indian Statistical Institute Kolkata

Kolkata, India

RESEARCH INTERN UNDER DR. SWAGATAM DAS, ECSU

2018 - 2020

- Implemented and experimented with several **Semantic Image Segmentation** approaches.
- Researched, developed and investigated **Differential Evolution** based methods for **Adversarial attacks** on SoTA image classifiers.

Artificial Intelligence Lab, Jadavpur University

Kolkata, India

RESEARCH ASSISTANT UNDER DR. AMIT KONAR

2018 - 2020

- Designed and implemented a Vision actuated system for detecting and grasping objects with brain commands.
- Published two papers on the application of Convolutional Neural Networks in Brain computer Interfacing.

Education

Carnegie Mellon University

Pittsburgh, USA

MASTER OF SCIENCE IN ROBOTICS, SCHOOL OF COMPUTER SCIENCE

2023 - Present

- Advisor : Dr. Martial Hebert, 100% scholarship**

Jadavpur University

Kolkata, India

BACHELOR OF ELECTRONICS AND TELECOMMUNICATION ENGINEERING

2016 - 2020

- Academia **CGPA : 9.35/10** | Standardised Test Scores : **GRE (331/340)** **TOEFL iBT (113/120)**

Skills & Interests

Programming Python, C, C++, MATLAB

Deep Learning Keras, PyTorch, TensorFlow, OpenCV, High-Performance clusters

Interests Computer Vision, Multimodal Learning, Reinforcement Learning, Deep Learning, Machine learning, A.I.

Academic Service

Reviewer **NeurIPS 2024, ICLR 2025, TPAMI**, Elsevier (IF : **8.139**), IET Computer Vision (IF : **1.95**)

Aug 2021 - Present

Publications

ReferEverything: Towards Segmenting Everything We Can Speak of in Videos

Under Submission

ANURAG BAGCHI, ZHIPENG BAO, YU-XIONG WANG, PAVEL TOKMAKOV, MARTIAL HEBERT

- Text-to-Video Diffusion model, Refer Segmentation, Video-Language grounding
[View paper][Project Page]

Video Diffusion Models Learn the Structure of the Dynamic World

Under Submission

ZHIPENG BAO, ANURAG BAGCHI, YU-XIONG WANG, PAVEL TOKMAKOV, MARTIAL HEBERT

- Text-to-Video Diffusion model, Video understanding
[View paper]

Hear Me Out: Fusional Approaches for Audio Augmented Temporal Action Localization

VISIGRAPP 2022

ANURAG BAGCHI, JAZIB MAHMOOD, DOLTON FERNANDES, RAVI KIRAN SARVADEVABHATLA

- Video Understanding, Temporal Action Localisation, Graph Neural Networks, Audio-Visual fusion, SoTA on **ActivityNet-v1.3** and **Thumos14**
[View paper][View code]

Autonomous grasping of 3-D objects by a vision-actuated robot arm using Brain-Computer Interface

Biomedical Signal

Processing and Control

ARNAB RAKSHIT; SHRAMAN PRAMANICK*; ANURAG BAGCHI*; SAUGAT BHATTACHARYYA

IF : 5.076

- RGB-D Grasp prediction, Object Detection, Inverse Kinematics, BCI, EEG classification [View paper]

Projects

Vision engine for object-attribute detection

Object detection - Faster RCNN - Image Classification

-Resnet50

INDEPENDENT

June 2020

- Developed a flexible framework for a two stage vision engine that performs coarse-grained object detection from RGB images and classifies the detected objects based on fine-grained attributes. Faster-RCNN is used for the initial detection of objects followed by parallel ResNet-50 based image classifiers that each detect the state of a different object attribute in a highly modular fashion.

Deep Power K-means for high dimensional clustering

Autoencoders - Deep Clustering - Representation Learning

INDIAN STATISTICAL INSTITUTE, ECSU

Aug 2020 - Dec 2020

- Developed a deep clustering framework based on Power K-means that jointly optimises the power means objective together with the auto-encoder loss from Deep K-means while simultaneously learning low dimensional cluster representations in each iteration. The differentiable surrogate in deep K-means is effectively replaced with the kolmogorov mean, while the annealing step is modified to achieve a series of smoother alternatives to the K-means objective.

Novel sparse whitebox adversarial attack on image classifier networks using differential evolution.

Deep Differential Evolution - Adversarial Attacks - Resnet -

VGG

INDIAN STATISTICAL INSTITUTE, ECSU

Jan 2020 - Aug 2020

- Implemented and investigated a tunable Differential Evolution based scheme for whitebox adversarial attacks on multiple state-of-the-art classifiers like Resnet 50, 101 and VGG-16.. The parameters for evolution are learned using a gradient descent scheme to reach the ideal balance between exploitation and exploration and increase the fooling rate.

Achievements

2023 **Full(100%) Scholarship for MS-Research**, Carnegie Mellon University

Pittsburgh, USA

2019 **University Topper in Final semester (grade : 10/10)**, Jadavpur University

Kolkata, India

2016 **Top 0.1%(99.9 percentile)**, State Engineering Entrance Exam

West Bengal

2016 **Top 0.4%(99.6 percentile)**, National Engineering Entrance Exam

India

Relevant Coursework

Undergraduate

Linear Algebra, Pattern Analysis and Machine Intelligence, Data Structures and Algorithms, Digital Image Processing, Probability and Statistics, Operating Systems, Digital Signal Processing

Graduate

3D Vision, Robot Learning, Advanced Computer Vision, Math for Robotics, Mechanics of Manipulation